

Eco

A Hardware-Software Co-design for In Situ Power Measurement on Low-end IoT Systems

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Agenda

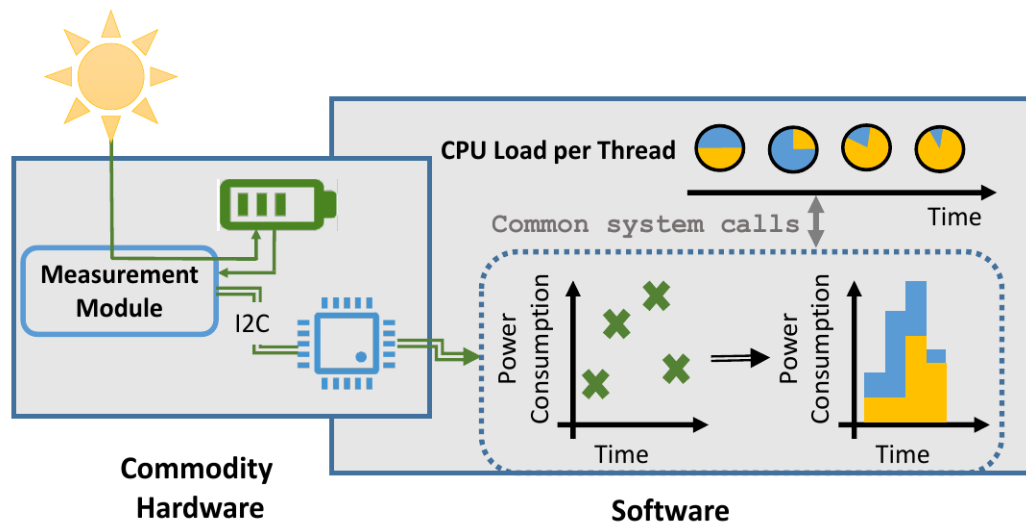
- Background on in situ power measurement
- Eco overview and software integration
- Evaluation of Eco
- Conclusion & outlook

Background

In situ power measurement & related work

Background

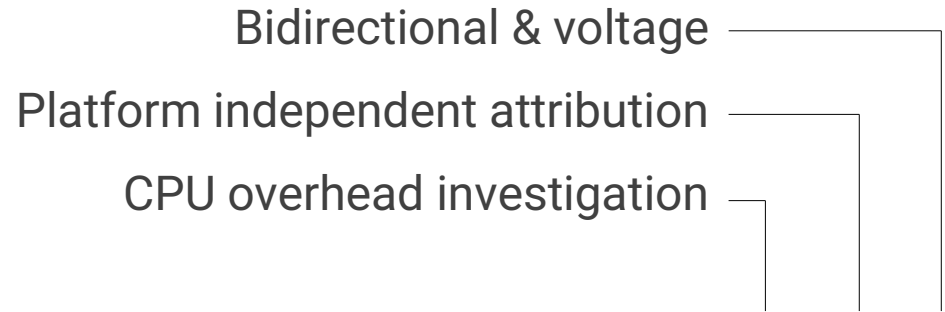
- Energy harvesting
- Energy management
 - Assessment
 - Attribution
 - Allocation
 - Prediction



Q1: "Can we do this with commodity components in a generic way?"

Q2: "How much overhead is introduced by that?"

Background - Related Work

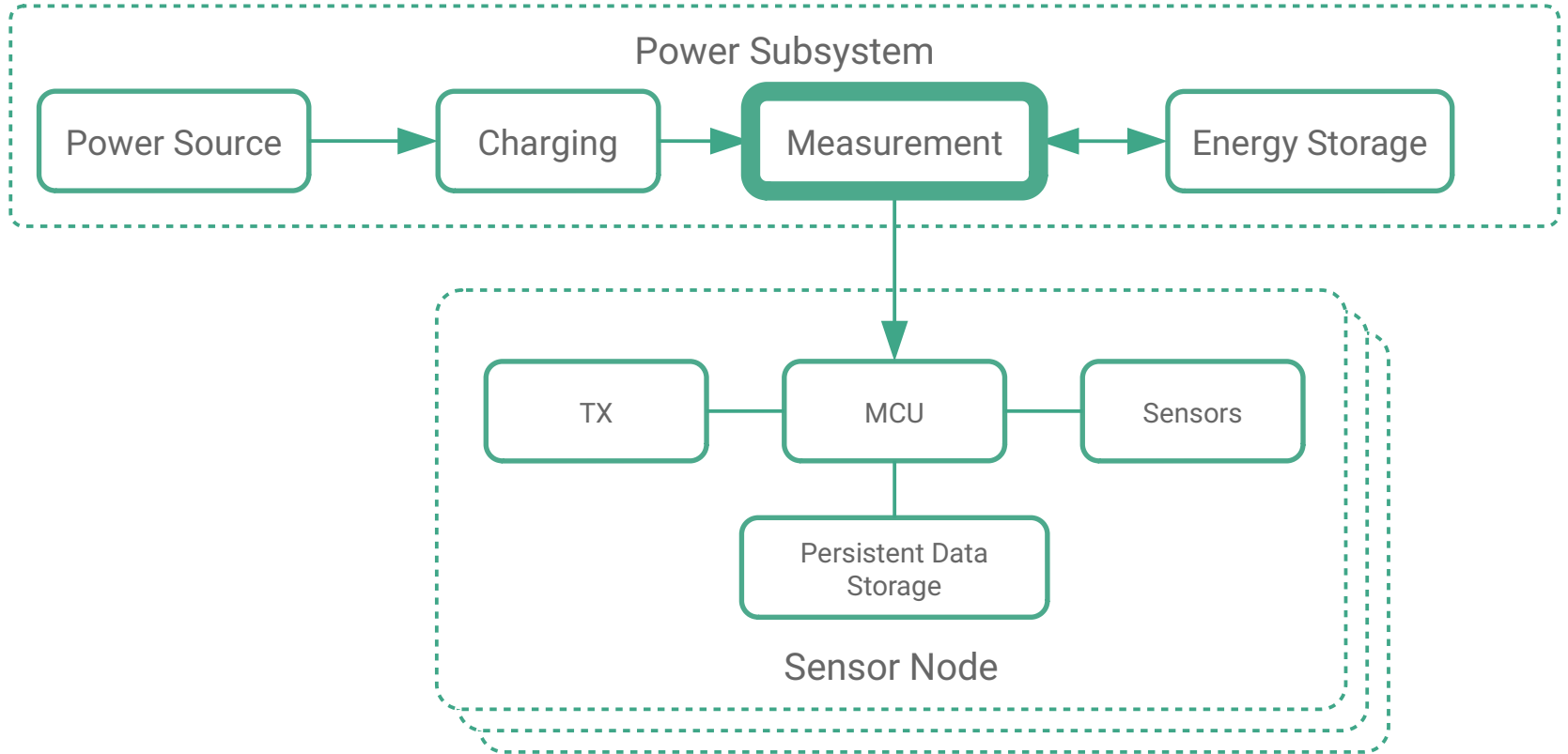


Solution	Description			
SPOT [13]	custom design; shunt voltage to frequency	✗	✗	✗
iCount [9]	SPOT principle; frequency from inductor	✗	✗	✗
Nemo [24]	additional MCU; tailored for TelosB	✓	✗	✗
Eco	commodity components; generic software	✓	✓	✓

Eco

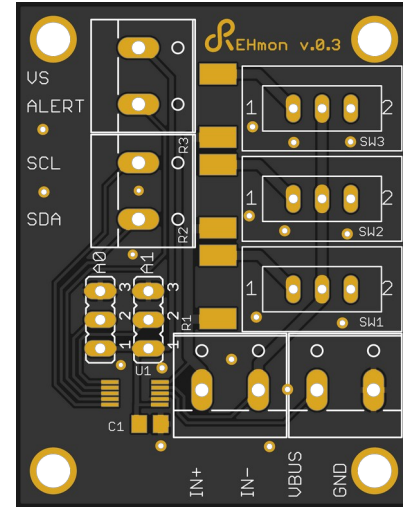
Architecture and Module Overview

Eco - System Overview



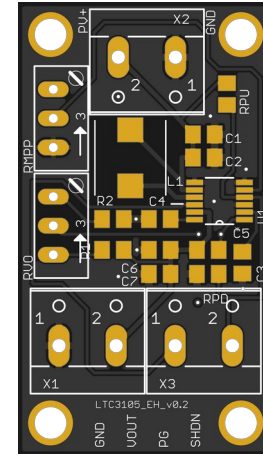
Eco – Measurement Module

- Bi-directional shunt monitor (INA226)
- Measures current and voltage
- I²C interface
- Current range selectable e.g. {40, 100, 500} mA
- Calibration
- Configurable conversion time and averaging
- Interrupt features for unattended operation



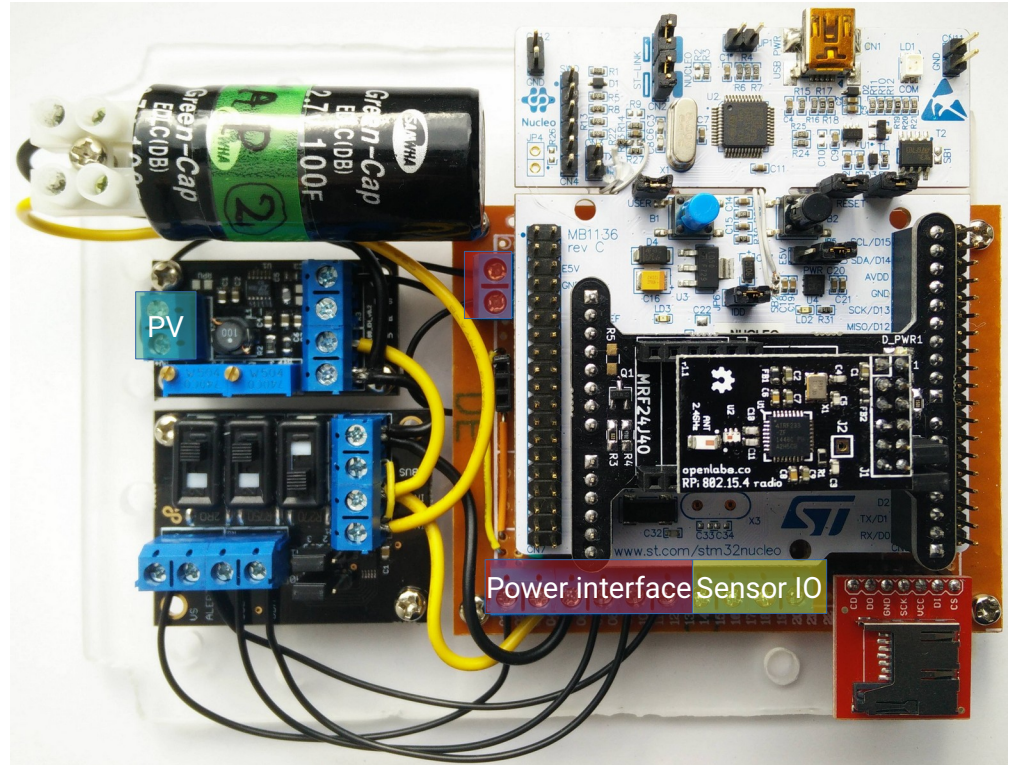
Eco – Charging Module

- 400 mA DC-DC step-up converter (LTC3105)
- Input working range: 225 mV – 5 V
- Suitable for various super caps and batteries
 - Vout: 2.2 V – 5.1 V
- Flexible adjustment for different PV-cells
 - $MPPC \leq 5 V$



Eco – Test System Orchestration

- MCU: plain nucleo-I476rg
- Green-Cap (100 F 2.7 V)
- Interface board (Morpho)
- μ SD-Card storage (SPI)



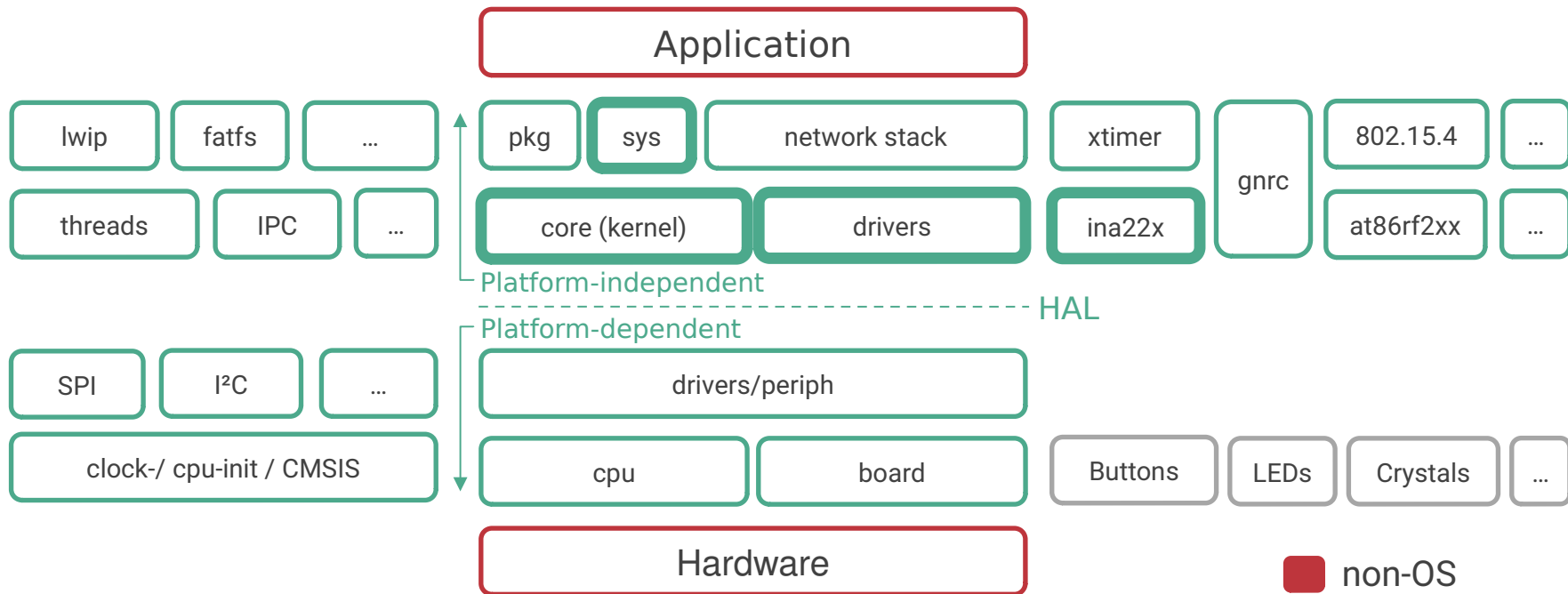
Eco

Software Integration

Eco – Software Integration

- Implemented on RIOT
- Explicit tracing
 - Measure consumption of code sections
 - Collect trace or aggregate
- Thread measurement
 - Continuous sampling
 - Attribute consumption to threads: new `es` command

RIOT



>> 100 different boards

- non-OS
- SW-module
- config

Evaluation of Eco

Methodology and Results

Evaluation of Eco - Methodology

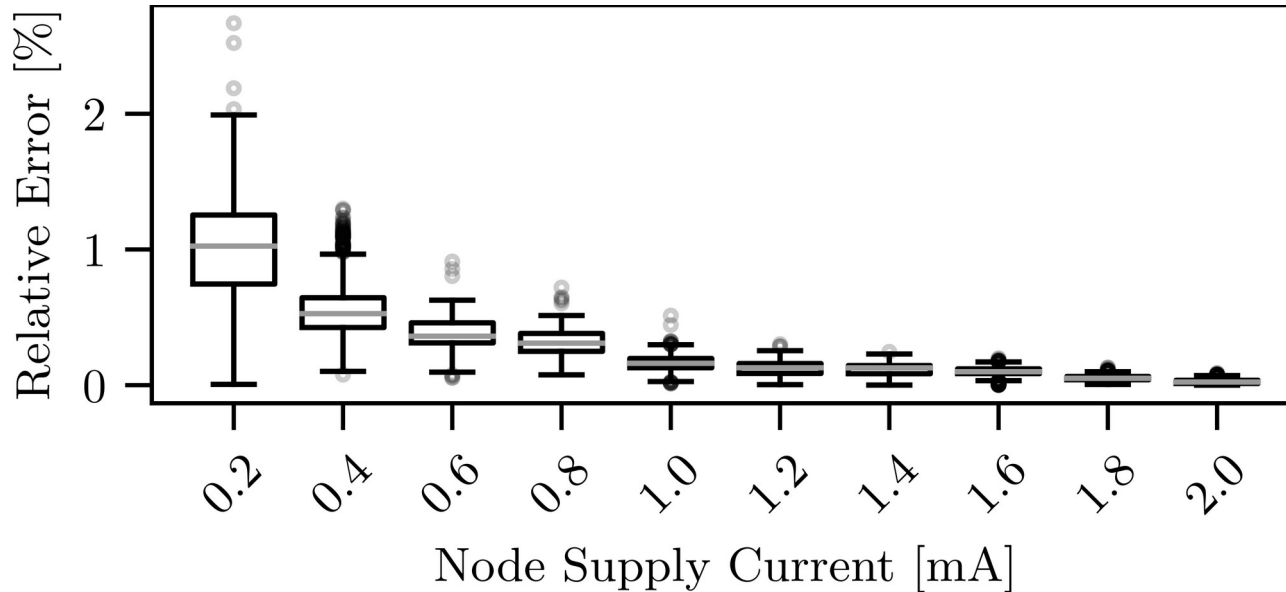
- Measurement accuracy

- Employ highly accurate reference (Keithley DMM7510)
- Vary current by applying voltage to fixed resistor (Siglent SPD3303C)

- Overhead

- Consumption: measurement module & communication bus
- CPU-utilization: impact of using generic I²C communication as interface
- Use `ps` command of RIOT to measure CPU-time and context switches

Measurement Accuracy

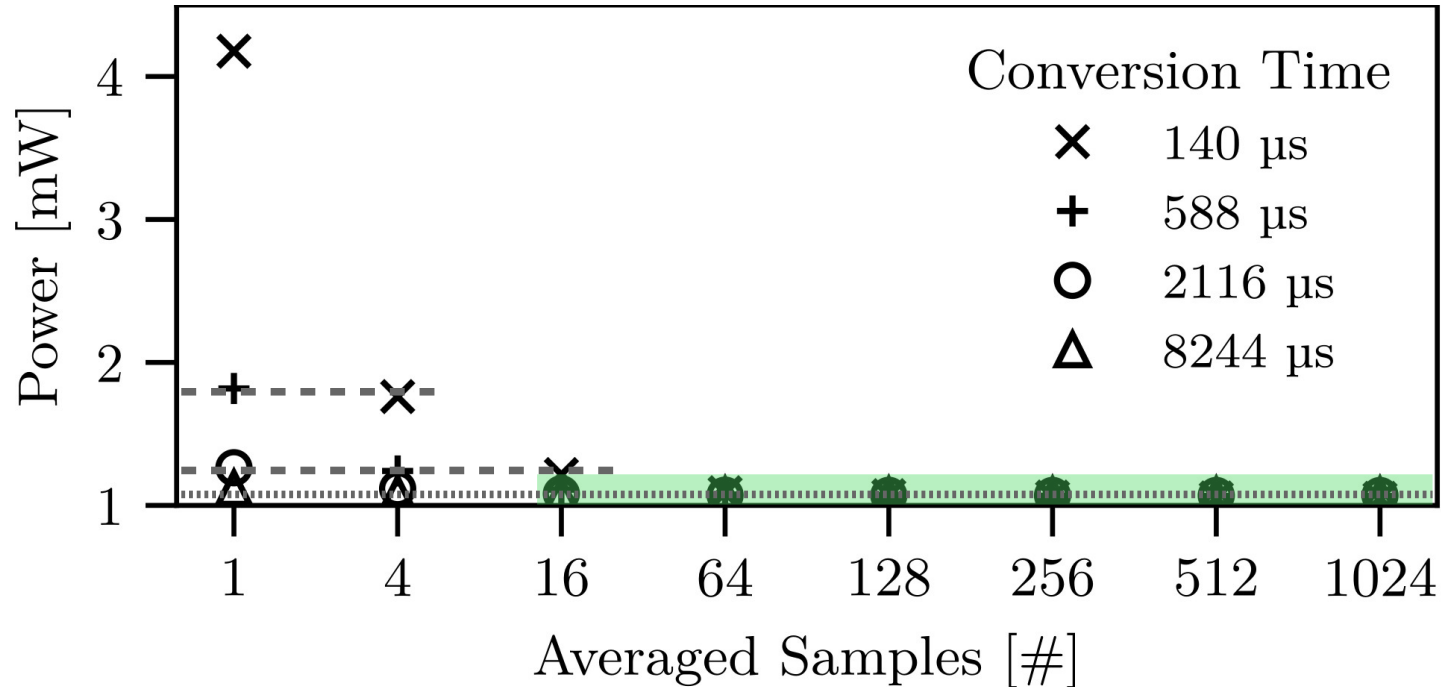


- 2 Ω shunt, 1.25 μA LSB
- 1 % median error @ 200 μA close to the LSB resolution

Power Overhead Contributors

- Shunt resistor losses
- Measurement module sampling
- I²C communication

Sampling & Communication Consumption

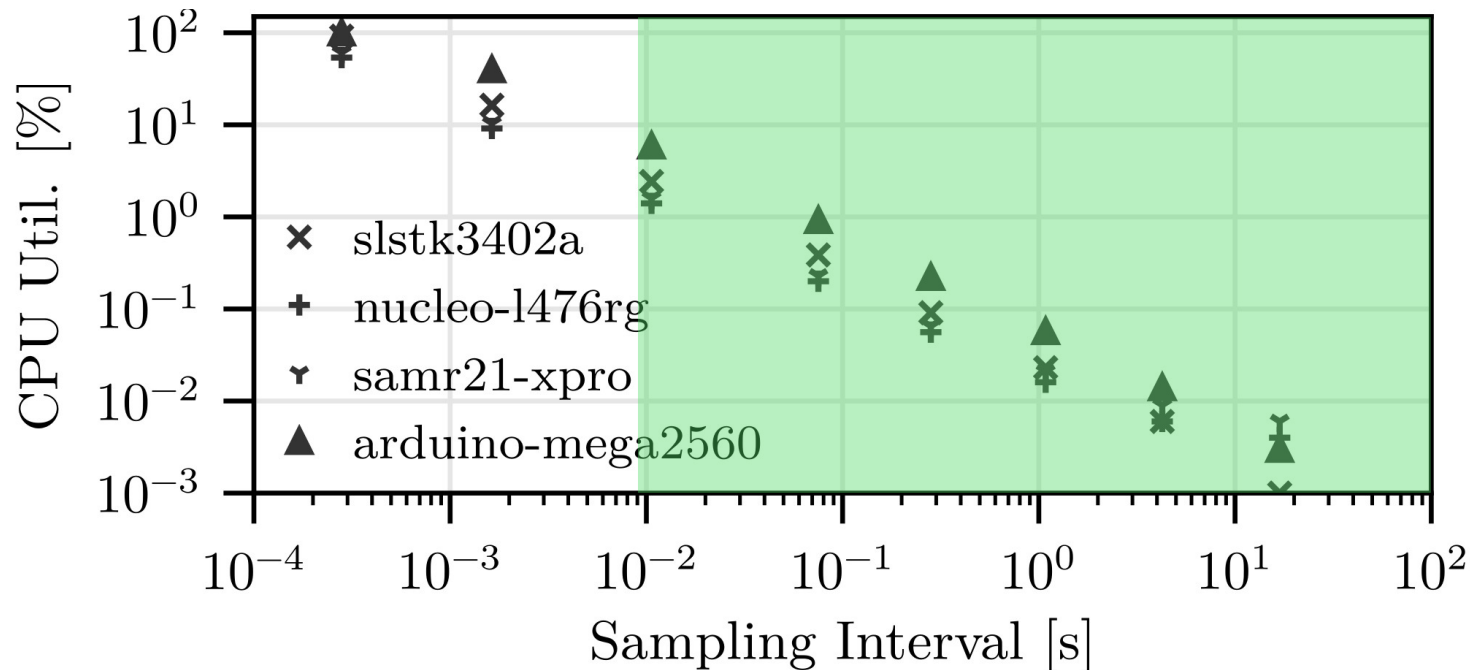


..... Baseline consumption with active sampling ~1 mW

- - - No significant difference between more averaging / sampling

■ Communication has no significant impact up to 588 μs @16 avg.

Cross-Platform CPU-Utilization

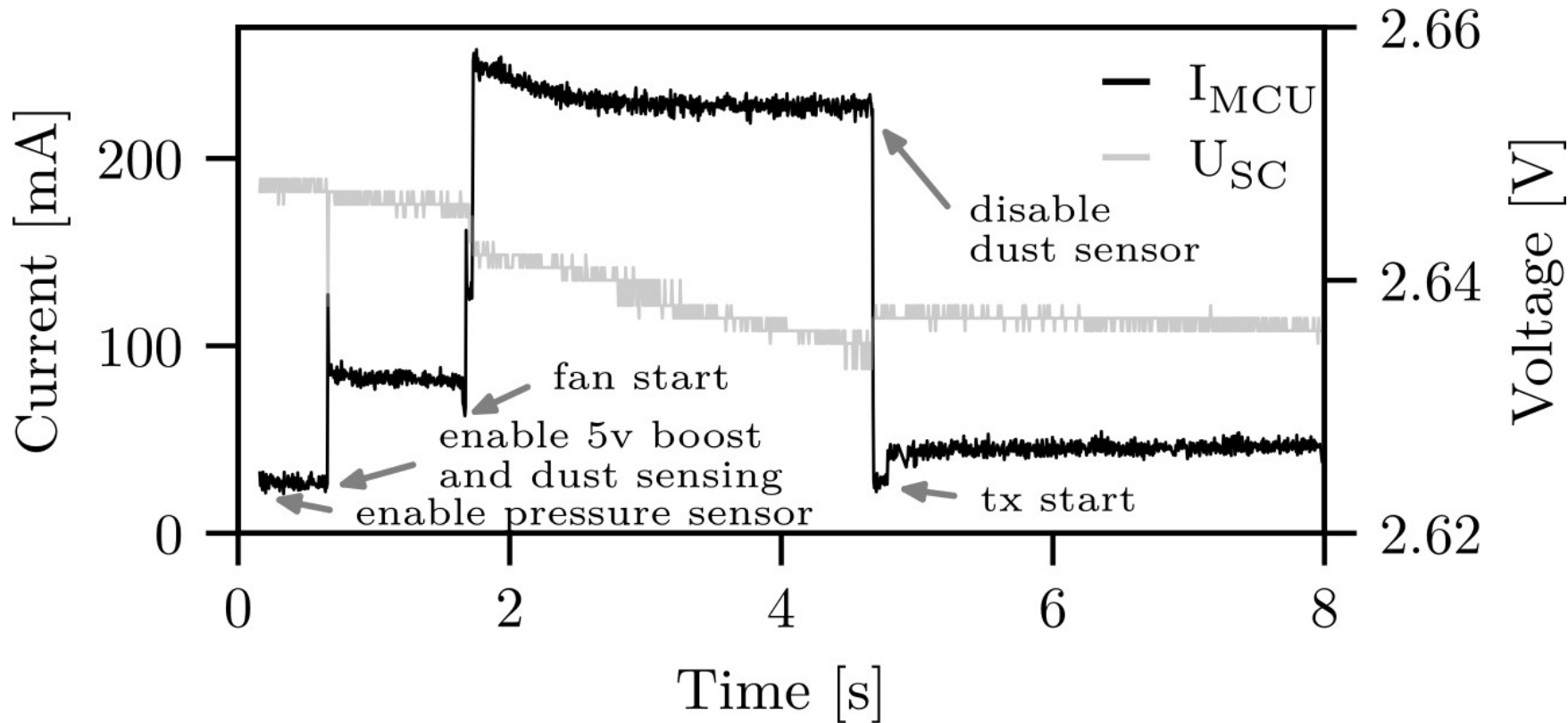


● Pessimistic scenario (separately read U and I, calculate P)

● Sampling every 10 ms possible on all platforms with CPU utilization between 1.4 % and 6 %

■ Communication consumption insignificant

Application Example: Active Dust Sensor



Conclusion

- Consumption of the communication-bus needs to be considered
 - Can be the dominant factor for very fast sampling
 - Negligible for reasonable self-measurement data rates
- Power measurement as generic system service
 - Compatible to virtually any MCU
 - CPU-overhead low enough even for very constrained devices
- Already usable in deployments

Outlook

- Dynamic sampling rate
- Improve thread attribution with state tracking
- Add layer for allocation & prediction

Discussion

Thank you for your attention!

Questions?

For more detailed comparison see our technical report: <https://arxiv.org/abs/1909.10609>