

# Towards Actor Programming for High-Performance Computing

Dominik Charousset

dominik.charousset@haw-hamburg.de

iNET RG, Department of Computer Science  
Hamburg University of Applied Sciences

August 2016



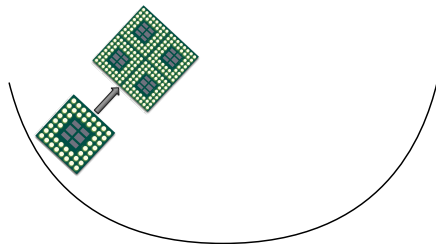
Hochschule für Angewandte  
Wissenschaften Hamburg  
*Hamburg University of Applied Sciences*



# Concurrency & Beyond

Developers face not one, but multiple trends:

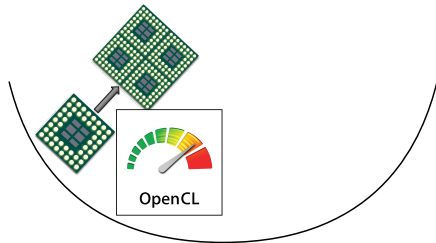
- **Concurrency:** More cores on desktops & mobiles
  - Accelerators: One binary, multiple instruction sets
  - Cloud & cluster computing: Highly distributed deployment
  - Embedded platforms: Distributed with limited node capabilities
- ⇒ Heterogeneous platforms, concurrency & distribution



# Concurrency & Beyond

Developers face not one, but multiple trends:

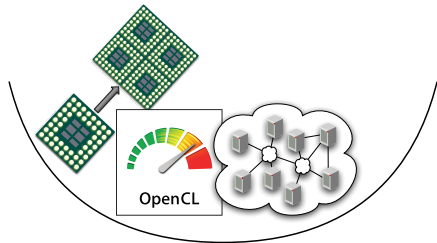
- Concurrency: More cores on desktops & mobiles
  - Accelerators: One binary, multiple instruction sets
  - Cloud & cluster computing: Highly distributed deployment
  - Embedded platforms: Distributed with limited node capabilities
- ⇒ Heterogeneous platforms, concurrency & distribution



# Concurrency & Beyond

Developers face not one, but multiple trends:

- Concurrency: More cores on desktops & mobiles
  - Accelerators: One binary, multiple instruction sets
  - Cloud & cluster computing: Highly distributed deployment
  - Embedded platforms: Distributed with limited node capabilities
- ⇒ Heterogeneous platforms, concurrency & distribution

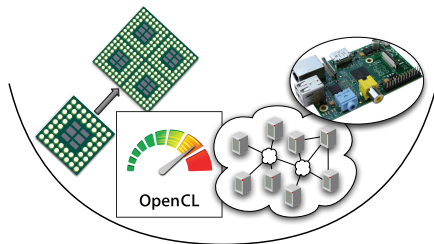


# Concurrency & Beyond

Developers face not one, but multiple trends:

- Concurrency: More cores on desktops & mobiles
- Accelerators: One binary, multiple instruction sets
- Cloud & cluster computing: Highly distributed deployment
- Embedded platforms: Distributed with limited node capabilities

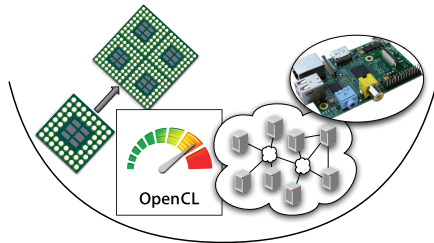
⇒ Heterogeneous platforms, concurrency & distribution



# Concurrency & Beyond

Developers face not one, but multiple trends:

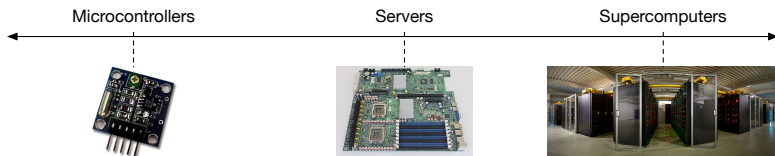
- Concurrency: More cores on desktops & mobiles
  - Accelerators: One binary, multiple instruction sets
  - Cloud & cluster computing: Highly distributed deployment
  - Embedded platforms: Distributed with limited node capabilities
- ⇒ Heterogeneous platforms, concurrency & distribution



# We Need Scalable Abstractions

Programming tools should enable users to scale applications

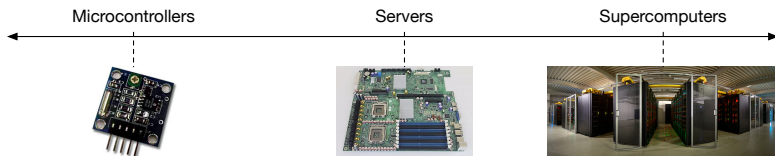
- Avoid race conditions by design (no locks!)
- Keep API stable when transitioning from one to many nodes
- Compose large systems out of small components (testability!)
- Provide a runtime that scales from the IoT up to HPC



# We Need Scalable Abstractions

Programming tools should enable users to scale applications

- Avoid race conditions by design (no locks!)
- Keep API stable when transitioning from one to many nodes
- Compose large systems out of small components (testability!)
- Provide a runtime that scales from the IoT up to HPC

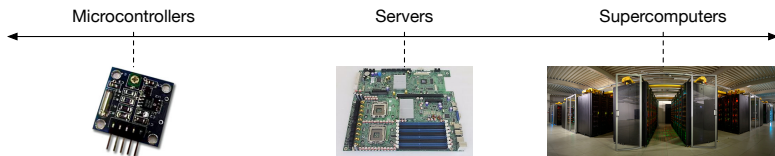




# We Need Scalable Abstractions

Programming tools should enable users to scale applications

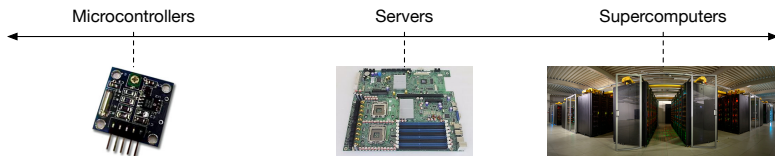
- Avoid race conditions by design (no locks!)
- Keep API stable when transitioning from one to many nodes
- Compose large systems out of small components (testability!)
- Provide a runtime that scales from the IoT up to HPC



# We Need Scalable Abstractions

Programming tools should enable users to scale applications

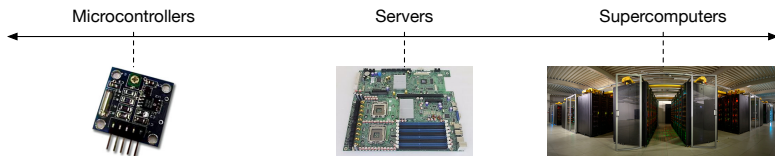
- Avoid race conditions by design (no locks!)
- Keep API stable when transitioning from one to many nodes
- Compose large systems out of small components (testability!)
- Provide a runtime that scales from the IoT up to HPC



# We Need Scalable Abstractions

Programming tools should enable users to scale applications

- Avoid race conditions by design (no locks!)
- Keep API stable when transitioning from one to many nodes
- Compose large systems out of small components (testability!)
- Provide a runtime that scales from the IoT up to HPC



# Agenda

- 1 The Actor Model
- 2 CAF – Actors in C++11
- 3 Case Study: CAF vs. OpenMPI
- 4 Towards HPC Actor Programming
- 5 Possible Stepping Stones
- 6 Conclusion

# The Actor Model

Actors are concurrent entities, that ...

- Communicate via message passing
- Do not share state
- Can create (“spawn”) more actors
- Can monitor other actors

# Brief History of the Actor Model

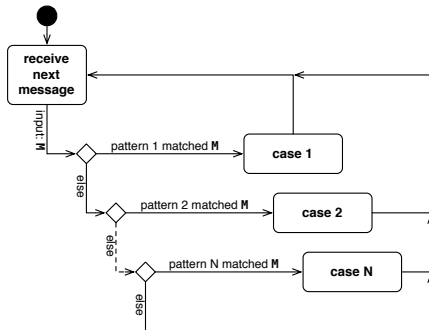
- Term was coined in 1973 by Hewitt, Bishop, and Steiger
- Roots in artificial intelligence & functional programming
- First widespread de facto implementation: Erlang (1986)
- Sudden peak of interest with advent of multicore machines

# Implications of the Actor Model

Actor: universal primitive for parallelism

- Actors run concurrently
- Lightweight actors outperform equivalent thread-based approaches
- Actor-based solutions often use divide & conquer strategies
- Deployment at runtime independent from application logic
- Communication between actors is network transparent

# Actor Programming

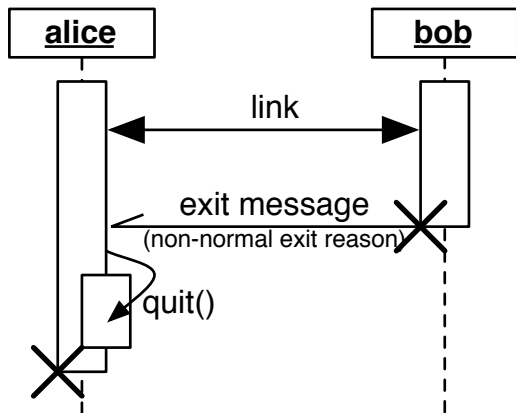


Actor Programming *is* Message-Oriented Programming

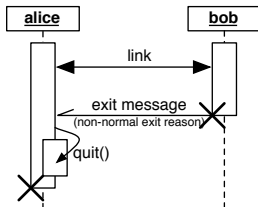
- Actors are active objects
- No direct method invocation, only messages
- Messages passing hides location of receiver



# Linking Actors



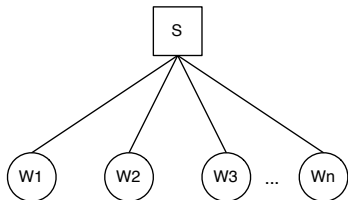
# Linking Actors



- Bidirectional monitoring
- Errors are propagated through exit messages
- When receiving an exit message:
  - Actors fail for the same reason per default
  - Actors can override default to handle failures manually
- Build systems where all actors are alive or have collectively failed

# Supervision Trees

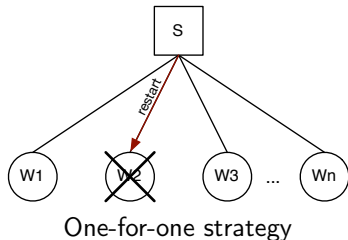
- High-level hierarchical error management in Erlang
- Upper actors (supervisor) monitor lower actors (workers)
- Policy-based restart of workers (possibly remotely) on failure



Example tree

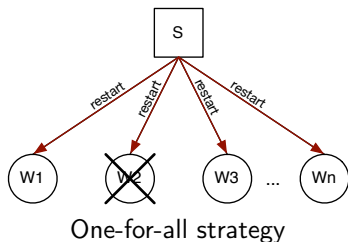
# Supervision Trees

- High-level hierarchical error management in Erlang
- Upper actors (supervisor) monitor lower actors (workers)
- Policy-based restart of workers (possibly remotely) on failure



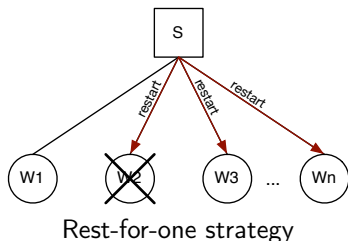
# Supervision Trees

- High-level hierarchical error management in Erlang
- Upper actors (supervisor) monitor lower actors (workers)
- Policy-based restart of workers (possibly remotely) on failure



# Supervision Trees

- High-level hierarchical error management in Erlang
- Upper actors (supervisor) monitor lower actors (workers)
- Policy-based restart of workers (possibly remotely) on failure



# Benefits of the Actor Model

- High-level, explicit communication between SW components
  - Robust software design: No locks, no implicit sharing
  - High level of abstraction for developing software
- Applies to concurrency *and* distribution
  - Abstraction over deployment
  - Messaging across heterogeneous HW components & networks
- Provides strong failure semantics
  - Hierarchical error management
  - Re-deployment at runtime

# Benefits of the Actor Model

- High-level, explicit communication between SW components
  - Robust software design: No locks, no implicit sharing
  - High level of abstraction for developing software
- Applies to concurrency *and* distribution
  - Abstraction over deployment
  - Messaging across heterogeneous HW components & networks
- Provides strong failure semantics
  - Hierarchical error management
  - Re-deployment at runtime



# Benefits of the Actor Model

- High-level, explicit communication between SW components
  - Robust software design: No locks, no implicit sharing
  - High level of abstraction for developing software
- Applies to concurrency *and* distribution
  - Abstraction over deployment
  - Messaging across heterogeneous HW components & networks
- Provides strong failure semantics
  - Hierarchical error management
  - Re-deployment at runtime

# Actors in High Performance Computing?

- HPC is getting more heterogeneous
  - Accelerators like NVIDIA Tesla & Intel Phi increase complexity
  - MPI and OpenMP only address individual problems at low level
- In-transit and in situ analysis is challenging
  - Low-level messaging APIs come with strong coupling
  - Actors can help to decouple and allow flexible deployment
- Actors systems can move computations instead of data
  - Data storages & networks are bottlenecks
  - Spawning actors near sources increases data locality

# Agenda

- 1 The Actor Model
- 2 CAF – Actors in C++11**
- 3 Case Study: CAF vs. OpenMPI
- 4 Towards HPC Actor Programming
- 5 Possible Stepping Stones
- 6 Conclusion

# About CAF

- Lightweight & fast actor model implementation
- First commit: 4 Mar 2011
- Developed at iNET research group (HAW Hamburg)
- > 40,000 lines of code<sup>1</sup>
- Active, international community

---

<sup>1</sup><https://www.openhub.net/p/actor-framework>

# Who is using CAF?

CAF currently focuses on infrastructure software

- Building blocks for essential software components
- Emphasis on reliability, efficiency and maintainability
- Relevant to users in both academia and industry

# CAF in MMOs



## Dual Universe<sup>2</sup>

- Single Shard Sandbox MMO
- Backend based on CAF
- Developed at Novaquark (Paris), currently in pre-alpha

---

<sup>2</sup><http://www.dual-thegame.com/>

# CAF in Network Forensics



## VAST: Visibility Across Space and Time<sup>3</sup>

- Platform for network forensics and incident response
- Distributed realtime indexing of network events
- Interactive, iterative queries on large data sets
- Developed at UC Berkeley, currently in pre-alpha

---

<sup>3</sup><http://vast.io>

# CAF in Communication Backends



Broker<sup>4</sup>: Bro's Messaging Library

- Implements Bro's high-level communication patterns
- Subscription-based communication model
- Distributed data store and event handling
- Developed at ICSI Berkeley, currently in beta

---

<sup>4</sup><https://github.com/bro/broker>



# CAF Actors are meant to Scale

- Flexible C++ runtime that adapts to deployment
  - Scale up/down from motes to high-end servers
  - Scale in/out from desktops to clusters
- Efficient program execution
  - Low memory footprint
  - Fast, lock-free mailbox implementation
- Transparent integration of OpenCL-based actors
  - Hide complexity of communicating with heterogeneous hardware
  - Offload work to GPGPUs simply by sending messages

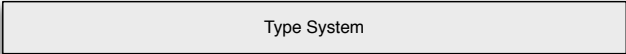
# CAF Actors are meant to Scale

- Flexible C++ runtime that adapts to deployment
  - Scale up/down from motes to high-end servers
  - Scale in/out from desktops to clusters
- Efficient program execution
  - Low memory footprint
  - Fast, lock-free mailbox implementation
- Transparent integration of OpenCL-based actors
  - Hide complexity of communicating with heterogeneous hardware
  - Offload work to GPGPUs simply by sending messages

# CAF Actors are meant to Scale

- Flexible C++ runtime that adapts to deployment
  - Scale up/down from motes to high-end servers
  - Scale in/out from desktops to clusters
- Efficient program execution
  - Low memory footprint
  - Fast, lock-free mailbox implementation
- Transparent integration of OpenCL-based actors
  - Hide complexity of communicating with heterogeneous hardware
  - Offload work to GPGPUs simply by sending messages

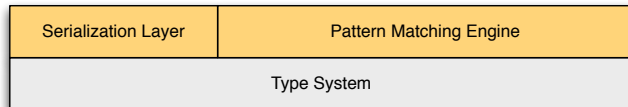
# Core Architecture of CAF



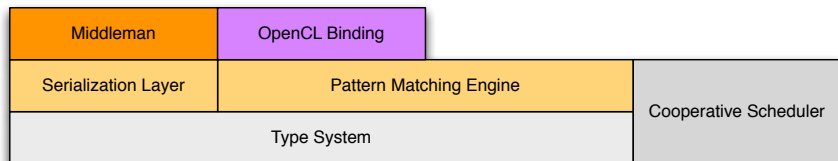
Type System

1/8

# Core Architecture of CAF

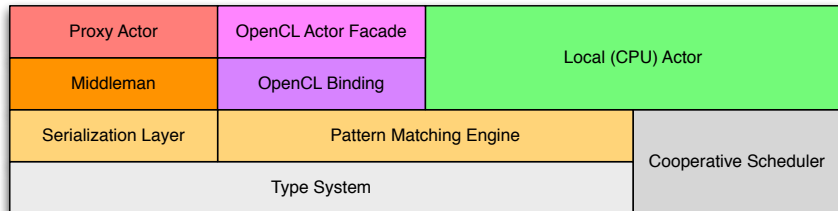


# Core Architecture of CAF



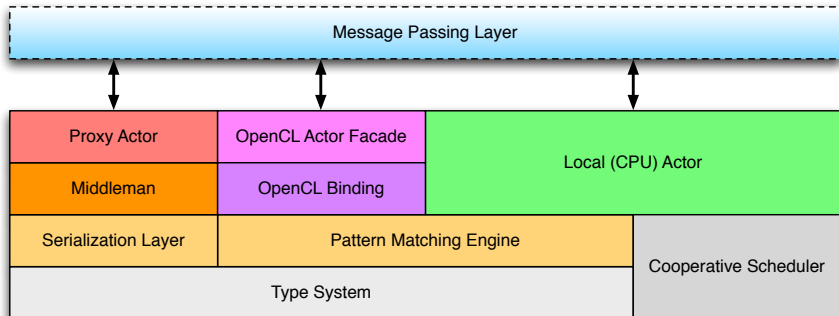
3/8

# Core Architecture of CAF



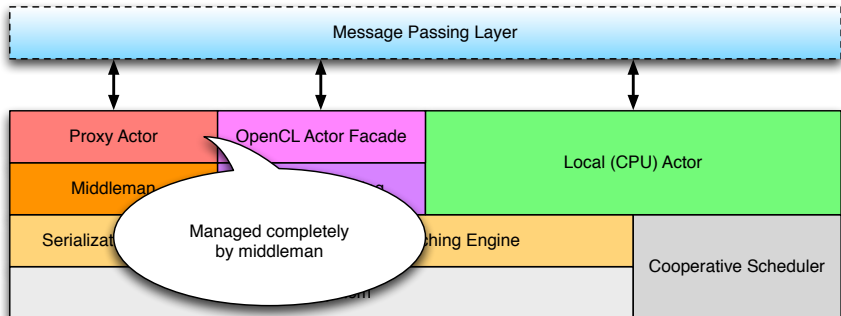
4/8

# Core Architecture of CAF

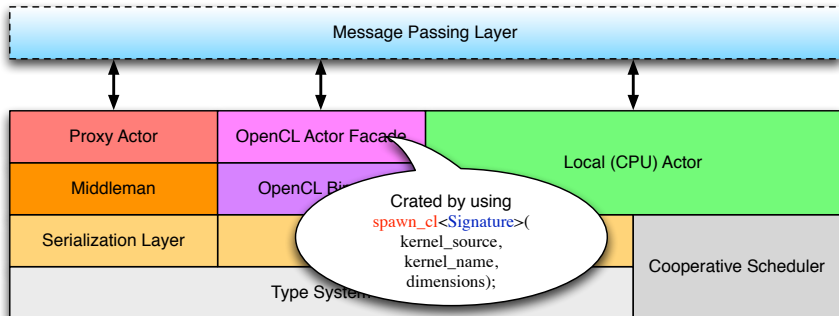




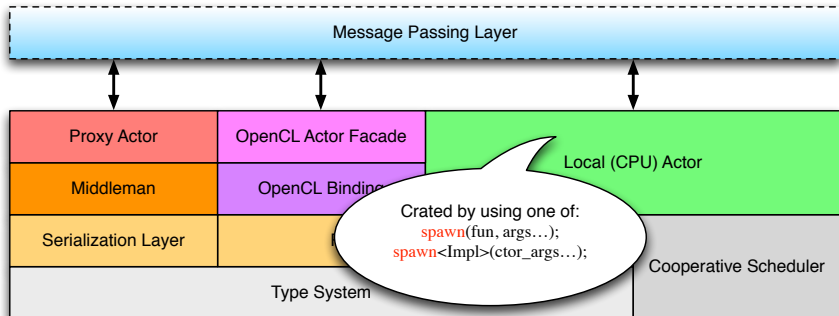
# Core Architecture of CAF



# Core Architecture of CAF



# Core Architecture of CAF



# Class vs. Actor Interfaces

```
class KeyValStore {  
public:  
    void set(Key k, Val v);  
    Val get(Key k) const;  
};
```

- Method invocation
- Race conditions likely
- Concurrent performance is a function of developer skill

```
using KeyValStore =  
    typed_actor<  
        reacts_to<set, Key, Val>,  
        replies_to<get, Key>  
        ::with<Val>>;
```

- Message passing
- Data race impossible
- Supports massively parallel access & remote invocation

# Class vs. Actor Interfaces

```
class KeyValStore {  
public:  
    void set(Key k, Val v);  
    Val get(Key k) const;  
};
```

- Method invocation
- Race conditions likely
- Concurrent performance is a function of developer skill

```
using KeyValStore =  
    typed_actor<  
        reacts_to<set, Key, Val>,  
        replies_to<get, Key>  
        ::with<Val>>;
```

- Message passing
- Data race impossible
- Supports massively parallel access & remote invocation

# Class vs. Actor Interfaces

```
class KeyValStore {  
public:  
    void set(Key k, Val v);  
    Val get(Key k) const;  
};
```

- Method invocation
- Race conditions likely
- Concurrent performance  
is a function of  
developer skill

```
using KeyValStore =  
    typed_actor<  
        reacts_to<set, Key, Val>,  
        replies_to<get, Key>  
        ::with<Val>>;
```

- Message passing
- Data race impossible
- Supports massively  
parallel access &  
remote invocation

# Class vs. Actor Interfaces

```
class KeyValStore {  
public:  
    void set(Key k, Val v);  
    Val get(Key k) const;  
};
```

- Method invocation
- Race conditions likely
- Concurrent performance is a function of developer skill

```
using KeyValStore =  
    typed_actor<  
        reacts_to<set, Key, Val>,  
        replies_to<get, Key>  
        ::with<Val>>;
```

- Message passing
- Data race impossible
- Supports massively parallel access & remote invocation

# Simple Calculator in CAF

```
using math_t = typed_actor<replies_to<int, int>::with<int>>;
math_t::behavior_type math_server() {
    return {
        [] (int a, int b) {
            return a + b;
        }
    };
}

void math_client(event_based_actor* self, math_t ms) {
    self->request(ms, 10s, 40, 2).then(
        [=] (int result) {
            cout << "40 + 2 = " << result << endl;
        }
    );
}

// system.spawn(math_client, system.spawn(math_server));
```



# Simple Calculator in CAF

```
using math_t = typed_actor<replies_to<int, int>::with<int>>;  
math_t::behavior_type math_server() {  
    return {  
        [](int a, int b) {  
            return a +  
        }  
    };  
}  
void math_client(event_based_actor* self, math_t ms) {  
    self->request(ms, 10s, 40, 2).then(  
        [=](int result) {  
            cout << "40 + 2 = " << result << endl;  
        }  
    );  
}  
// system.spawn(math_client, system.spawn(math_server));
```

typedef with interface definition  
for convenience

# Simple Calculator in CAF

```
using math_t = typed_actor<replies_to<int, int>::with<int>>;
math_t::behavior_type math_server() {
    return {
        [] (int a, int b) {
            return a + b;
        }
    };
}
void server::start() {
    self, math_t ms) {
        ms(
            cout << "40 + 2 = " << result << endl;
        }
    );
}
// system.spawn(math_client, system.spawn(math_server));
```

return message handler for  
incoming messages (used until  
replaced or actor is done)

# Simple Calculator in CAF

```
using math_t = typed_actor<replies_to<int, int>::with<int>>;  
math_t::behavior_type math_server() {  
    return {  
        [](int a, int b) {  
            return a + b;  
        }  
    };  
}  
vo * self, math_t ms) {  
    self->request(ms, 100, 10, 2).then(  
        [=](int result) {  
            cout << "40 + 2 = " << result << endl;  
        }  
    );  
}  
// system.spawn(math_client, system.spawn(math_server));
```

types of message handlers  
must match interface definition

# Simple Calculator in CAF

```
using math_t = typed_actor<replies_to<int, int>::with<int>>;
math_t::behavior_type math_server() {
    return {
        [] (int request) {
            return request + 2;
        }
    };
}

void math_client(event_based_actor* self, math_t ms) {
    self->request(ms, 10s, 40, 2).then(
        [=] (int result) {
            cout << "40 + 2 = " << result << endl;
        }
    );
}

// system.spawn(math_client, system.spawn(math_server));
```

send a message and then  
wait for response  
(using a "one-shot handler")

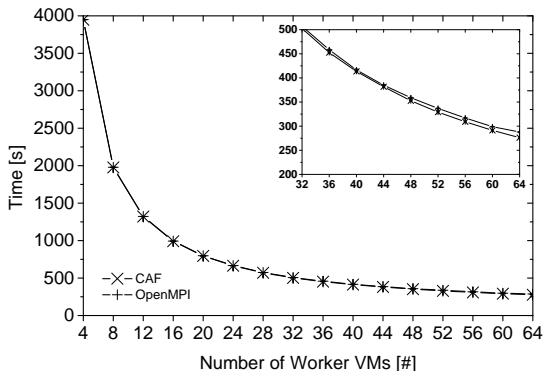
# Agenda

- 1 The Actor Model
- 2 CAF – Actors in C++11
- 3 Case Study: CAF vs. OpenMPI**
- 4 Towards HPC Actor Programming
- 5 Possible Stepping Stones
- 6 Conclusion

# Case Study: Distributed Mandelbrot

- Calculate images of the Mandelbrot set in C++
- Simple, highly distributable algorithm
- Distributed using (1) CAF and (2) OpenMPI
  - Same source code for calculation
  - Only the message passing layers differ

# Case Study Results



- Both implementations exhibit equal scaling behavior
- Doubling the number of worker nodes halves the runtime
- CAF slightly faster despite higher level of abstraction

# Case Study Discussion

- Higher level of abstraction does not imply lower performance
- Message passing in CAF has minimal overhead
- Relatively small number of nodes in test setup (64)
- No other MPI implementations tested (e.g. Intel MPI)
- CAF not yet ready for HPC technologies such as Infiniband



# Agenda

- 1 The Actor Model
- 2 CAF – Actors in C++11
- 3 Case Study: CAF vs. OpenMPI
- 4 Towards HPC Actor Programming**
- 5 Possible Stepping Stones
- 6 Conclusion

# Goal: Data-driven Actors

- User defines high-level data model
- Runtime instantiates actors on demand
- Self-organizing runtime instead of hard-wired messaging
- Maximize data locality by moving actors, not data
- Build extensible message flows and computation steps
- Tools for visualization of system state & live data

# Benefits for HPC Developers

- Reduced complexity
- Faster development cycles
- Domain-specific data models
- Composability and re-usability

# Challenges for CAF

- HPC network backend (Infiniband)
- DSL for defining data models and task dependencies
- New tools for visualization and debugging
- Optimize CAF internals further, particularly memory access
- Scalable algorithms for self-organizing actors

# Agenda

- 1 The Actor Model
- 2 CAF – Actors in C++11
- 3 Case Study: CAF vs. OpenMPI
- 4 Towards HPC Actor Programming
- 5 Possible Stepping Stones**
- 6 Conclusion

# Improve Existing HPC Tool

- Parallel actor pipelines as first step
- Model data processing steps as actors
- Gain experience with “less critical” post processing
- Example: parallel Climate Data Operators (CDO) with CAF

# Integrate CAF into Existing Middleware

- Deploy actors in data streams of Net-CDF4/HDF5
- Re-use data processing actors for in-transit operations
- Proof of concept for dynamic in-transit work flows with CAF

# Agenda

- 1 The Actor Model
- 2 CAF – Actors in C++11
- 3 Case Study: CAF vs. OpenMPI
- 4 Towards HPC Actor Programming
- 5 Possible Stepping Stones
- 6 Conclusion**



# Conclusion

- We believe actor programming is a good fit for HPC
- A high level of abstraction can increase robustness & efficiency
- Data-driven actors are also relevant in smaller deployments
- The most important first step for us is finding the right community

# Conclusion

- We believe actor programming is a good fit for HPC
- A high level of abstraction can increase robustness & efficiency
- Data-driven actors are also relevant in smaller deployments
- The most important first step for us is finding the right community

# Conclusion

- We believe actor programming is a good fit for HPC
- A high level of abstraction can increase robustness & efficiency
- Data-driven actors are also relevant in smaller deployments
- The most important first step for us is finding the right community

# Conclusion

- We believe actor programming is a good fit for HPC
- A high level of abstraction can increase robustness & efficiency
- Data-driven actors are also relevant in smaller deployments
- The most important first step for us is finding the right community

# Thank you for your attention!

Home page: <http://actor-framework.org>

iNET research group: <http://inet.cpt.haw-hamburg.de>

Sources: <https://github.com/actor-framework/actor-framework>